## SAFE VIRTUAL MACHINE FOR C

# The ultra small target independent Virtual Machine

Dynamic code in C for deeply embedded and distributed systems

Altreonic is breaking again new grounds by complementing its OpenComRTOS with the capability to run processor independent code. The code is binary compiled and linked C code, resulting in only 3.8 Kbytes for the safety enhanced Virtual Machine task running the code. As the native OpenComRTOS also only requires Kbytes, this capability opens new possibilities for memory and power constrained embedded systems.

### Capabilities:

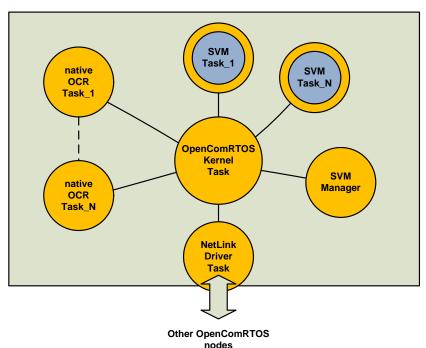
- Loading and running code on a remote node without halting it
- Dynamic code loading at runtime
- · Dynamic task migration at runtime
- Transparent communication with native OpenComRTOS tasks on the same or on remote nodes
- Safe execution: SafeVM tasks cannot violate memory boundaries.

Future releases will also support calling native functions for maximum performance and direct execution of the binary images on the target processor (ARM only).

## **Applications:**

- Remote diagnostics
- · Fail safe and fault tolerant control
- Processor independent programming

Thanks to the use of OpenComRTOS, SafeVM tasks can operate system wide across all nodes in the network. The user can also put several SafeVM tasks on the same node.



#### How it works:

The SafeVM capability is provided by a SafeVM task manager that can start and stop the task. monitor their status and interact with the SafeVM host task. The latter is composed of a safe VM execution module and the actual SafeVM task. The SafeVM task itself interacts with the rest of the node through precompiled services, including the standard Open-ComRTOS services.

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#### **Available SafeVM task services:**

#### SVM LoadTask

// loads the SVM task in the SVM workspace

#### SVM StartTask

// starts the SVM task

#### SVM StopTask

// Stops the SVM task

#### SVM ClearTask

// Clears the workspace memory of the SVM // Equivalent to unloading the SVM task

#### SVM GetErrorInfo

// Returns the last error code

## SVM GetState

// Returns the current state of the SVM

#### OpenComRTOS services

OpenComRTOS services operate transparently across a networked or multicore system.

Services include: preemptive priority based task scheduling, events, counting semaphores, fifos, resource locks with support for priority inheritance, packet pools, memory pools.

See the OpenComRTOS datasheets and manuals for more details.

The SVM task can be written using all features of ANSI-C, including libraries.

## Relative performance

Measured on ARM Cortex M3:

Program code for SVM

(manager + execution module): 3.8 KBytes

Relative RTOS performance:

Example semaphore loop with one task being a SVM Task: about 7x slower.

Computational performance:

depends on application code.

# **Example program:**

This example first loads first a SVM Task on the node, waits until it stops, and then uploads a new SVM Task to the node and starts it.

```
#include <SVM HostService/</pre>
          SVM HostClient.h>
void Task1 entry(L1 TaskArguments Args)
FILE *fo;
SVM STATE state;
// TASK1 - binary file with image
fo = fopen(SVM TASK1,"r");
assert (fo!=NULL);
// buffer for storing program
L1 UINT32 buffer[128];
L1 UINT32 n = fread(buffer,
              sizeof(L1 UINT32),
              128,
               fo);
assert(n!=0);
// send task to SVM task
SVM LoadTask(SVM Manager,
                 n*4,
                 5000);
// start task on the node
SVM_StartTask(SVM_Manager);
^-// waiting until first task stops
     SVM GetState (SVM, &state);
     if (state==VSP VM ERROR)
     exit(1);
while(state!=SVM VM STOPPED);
// Load second task
// SVM TASK2 - binary file with image
   fo = fopen(SVM TASK2,"r");
assert(fo!=NULL);
n = fread(buffer,
          sizeof(L1 UINT32),
          128,
          fo);
assert(n!=0);
SVM LoadTask(SVM Manager,
                 buffer.
                 n*4,
                  5000);
```

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